

Simultaneous Peak and Average Power Minimization during Datapath Scheduling for DSP Processors

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Outline of the talk

- Introduction
- Related work
- Target architecture
- Power model
- ILP formulations
- Scheduling algorithm
- Experimental results



Peak power ?

The peak power is the maximum power consumption of the circuit at any instance during its execution.



Average power ?

Total energy consumed per unit time.



Why peak power reduction ?

Reduction of peak power consumption is essential :

- (i) to maintain supply voltage levels
- (ii) to increase reliability
- (iii) to use smaller heat sinks
- (iv) to make packaging cheaper



Why average power reduction ?

The average power reduction is essential for the following reasons :

- (i) to increase battery life time,
- (ii) to enhance noise margin,
- (iii) to reduce cooling and energy costs,
- (iv) to reduce use of natural resources and
- (v) to increase system reliability



Related work

(Energy efficient scheduling using voltage reduction)

- Chang and Pedram [3], 1997 – Dynamic programming
- Johnson and Roy [4], 1997 – ILP based MOVER algorithm using multiple supply voltages
- Lin, Hwang and Wu [6], 1997 – ILP and heuristic for variable voltages (VV) and multicycling (MC)
- Mohanty and Ranganathan [10], 2003 – Heuristic based using multiple voltage and dynamic clocking

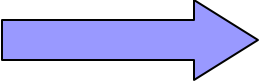


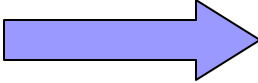
Related work

(Peak Power efficient scheduling)

- Martin and Knight [7,8,9], 1996 – Simultaneous assignment and scheduling
- Raghunathan, Ravi and Raghunathan [10], 2001 – data monitor operations in VHDL
- Mohanty, Ranganathan & Chappidi [12], 2003 – ILP based using multiple voltages, dynamic clocking & multicycling
- Shiue [15], 2000 – ILP based and modified force direct scheduling for peak power minimization
- Shiue and Chakrabarti [16], 2000 - ILP model to minimize peak power and area for single voltage

Voltage, Frequency and Power Trade-offs

(i) voltage reduction  increase in delay

(ii) frequency reduction  reduction in power not energy (and increase in delay)

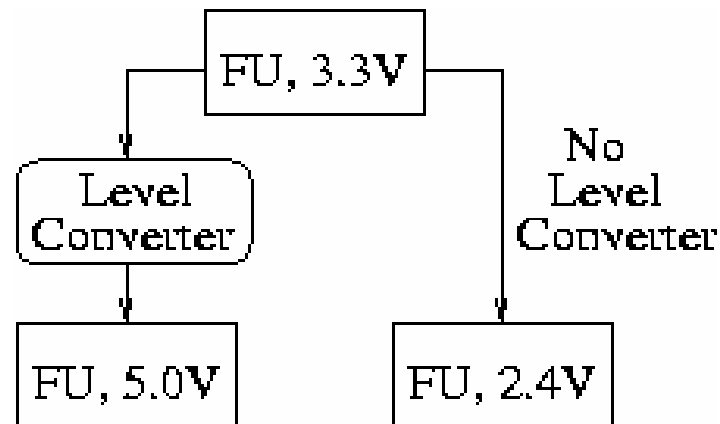
“Beyond of (i) and (ii) reduction of switching capacitance can be considered.”



What is our approach ?

Adjust the frequency and reduce the supply voltage for peak and average power reduction during datapath scheduling.

Target architecture



- ❑ Each functional unit has one register and one multiplexor.
- ❑ The register and the multiplexor operate at the same voltage level as that of the functional units.
- ❑ Level converters are used when a low-voltage functional unit is driving a high-voltage functional unit.
- ❑ Operational delay of a FU : $(d_{FU} + d_{Mux} + d_{Reg} + d_{Conv})$.



Power model : Notations

For a DFG let us assume :

c = any control step or clock cycle in DFG

N = total number of control steps in the DFG

R_c = number of resources active in step c

f_c = cycle frequency for control step c

$\alpha_{i,c}$ = switching at resource i active in step c

$C_{i,c}$ = load capacitance of resource i active in step c

$V_{i,c}$ = operating voltage of resource i active in step c



Cycle power (P_c)

The power consumption for any control step c is given by,

$$P_c = \sum_{i=\{1 \rightarrow R_c\}} \alpha_{i,c} C_{i,c} V_{i,c}^2 f_c$$

Peak power (P_p)

The peak power consumption of the DFG is the maximum power consumption over all the control steps,

$$P_p = \text{maximum}(\mathbf{P}_c)_{c=\{1 \rightarrow N\}}$$

Using the above two equations the peak power consumption of the DFG is described as,

$$P_p = \text{maximum} \left(\sum_{i=\{1 \rightarrow Rc\}} \alpha_{i,c} \mathbf{C}_{i,c} \mathbf{V}_{i,c}^2 \mathbf{f}_c \right)_{c=\{1 \rightarrow N\}}$$



Average power (P_a)

Characterized as mean of the cycle power (P_c) :

$$\begin{aligned} P_a &= 1/N \left(\sum_{c=\{1 \rightarrow N\}} P_c \right) \\ &= 1/N \left(\sum_{c=\{1 \rightarrow N\}} \sum_{i=\{1 \rightarrow R_c\}} \alpha_{i,c} C_{i,c} V_{i,c}^2 f_c \right) \end{aligned}$$



Objective ?

To minimize :

Peak power (P_p) + Average power (P_a)

ILP formulations for MVDFC : notations

O : total number of operations in the DFG

o_i : any operation i , $1 \leq i \leq O$

$F_{k,v}$: functional unit of type k operating at voltage level v

$M_{k,v}$: maximum number of functional units of type k operating at voltage level v

S_i : as soon as possible time stamp for the operation o_i

E_i : as late as possible time stamp for the operation o_i

$P(i,v,f)$: power consumption due to operation o_i using resource $F_{k,v}$, which is operating at frequency f

$x_{i,c,v,f}$: decision variable which takes the value of 1 if operation o_i is scheduled in control step c using the functional unit $F_{k,v}$ and c has frequency f



ILP formulations for MVDFC

- (i) Objective Function
- (ii) Uniqueness Constraints
- (iii) Precedence Constraints
- (iv) Resource Constraints
- (v) Frequency Constraints
- (vi) Peak Power Constraints

ILP formulations for MVDFC

Objective Function :

$$\text{Minimize } (P_p + 1/N \sum_c \sum_v \sum_i \sum_f x_{i,c,v,f} * P(i,v,f))$$

Uniqueness Constraints :

ensure that every operation o_i is scheduled to one unique control step and represented as,
 $\forall i, 1 \leq i \leq O, \sum_c \sum_v \sum_f x_{i,c,v,f} = 1$

ILP formulations for MVDFC

Precedence Constraints :

guarantee that for an operation o_i , all its predecessors are scheduled in an earlier control step and successors are scheduled in an later control step ; $\forall i,j, o_i$ belong to $\text{Pred}(o_j)$,
$$\sum_v \sum_f \sum_{\{d=S_i \rightarrow E_j\}} d \cdot x_{i,c,v,f} - \sum_v \sum_f \sum_{\{d=S_j \rightarrow E_j\}} e \cdot x_{j,c,v,f} \leq -1$$

Resource Constraints :

make sure that no control step contains more than $F_{k,v}$ operations of type k operating at voltage v and are enforced as, $\forall c, 1 \leq c \leq N$ and $\forall v$,
$$\sum_{\{i \in F_{k,v}\}} \sum_f x_{i,c,v,f} \leq M_{k,v}$$

ILP formulations for MVDFC

Frequency Constraints :

lower operating voltage functional unit can not be scheduled in a higher frequency control step; these constraints are expressed as, $\forall i, 1 \leq i \leq O$, $\forall c, 1 \leq c \leq N$, if $f < v$, then $x_{i,c,v,f} = 0$.

Peak Power Constraints :

ensure that the maximum power consumption of the DFG does not exceed P_p for any control step and we enforce these constraints as follows, $\forall c, 1 \leq c \leq N$ and $\forall v$,

$$\sum_{\{i \in F_{k,v}\}} \sum_f x_{i,c,v,f} P(i,v,f) \leq P_p$$

ILP formulations for MVMC : notations

O : total number of operations in the DFG

o_i : any operation i , $1 \leq i \leq O$

$F_{k,v}$: functional unit of type k operating at voltage level v

$M_{k,v}$: maximum number of functional unit $F_{k,v}$

S_i : as soon as possible time stamp for the operation o_i

E_i : as late as possible time stamp for the operation o_i

$P(i,v,f_{clk})$: power consumption due to operation o_i using resource $F_{k,v}$

$y_{i,v,l,m}$: decision variable which takes value of 1 if operation o_i is using $F_{k,v}$ and scheduled in control steps $l \rightarrow m$

$L_{i,v}$: latency for operation o_i using $F_{k,v}$



ILP formulations for MVMC

- (i) Objective Function
- (ii) Uniqueness Constraints
- (iii) Precedence Constraints
- (iv) Resource Constraints
- (v) Peak Power Constraints

ILP formulations for MVMC

Objective Function :

$$\text{Minimize } (P_p + 1/N \sum_i \sum_j \sum_v y_{i,v,l,(l+L_{i,v}-1)})$$

Uniqueness Constraints :

ensure that every operation o_i is scheduled to appropriate control steps within the range (S_i, E_i) and represented as, $\forall i, 1 \leq l \leq O,$

$$\sum_v \sum_{\{l=S_i \rightarrow (S_i+E_i+1-L_{i,v})\}} y_{i,v,l,(l+L_{i,v}-1)} = 1$$

ILP formulations for MVMC

Precedence Constraints :

guarantee that for an operation o_i , all its predecessors are scheduled in an earlier control step and its successors are scheduled in an later control step and are; $\forall i,j$, o_i belong to $\text{Pred}(o_j)$,

$$\sum_v \sum_{\{l=S_i \rightarrow E_j\}} (l+L_{i,v}-1) y_{i,v,l,(l+L_{i,v}-1)} - \sum_v \sum_{\{l=S_j \rightarrow E_j\}} l y_{j,v,l,(l+L_{j,v}-1)} \leq -1$$

ILP formulations for MVMC

Resource Constraints :

make sure that no control step contains more than $F_{k,v}$ operations of type k operating at voltage v and are enforced as, $\sum_{\{i \in F_{k,v}\}} \sum_l y_{i,v,l,(l+L_{i,v}-1)} \leq M_{k,v}$

Peak Power Constraints :

ensure that the maximum power consumption of the DFG does not exceed P_{peak} for any control step and we enforce these constraints as follows, for all c , $1 \leq c \leq N$ and for all v ,
 $\sum_{\{i \in F_{k,v}\}} \sum_v y_{i,v,l,(l+L_{i,v}-1)} P(i,v,f_{clk}) \leq P_p$



Scheduling algorithm

Input :

- (i) unscheduled DFG
- (ii) resource constraints
- (iii) number of voltage levels
- (iv) number of frequencies
- (v) delay of resources

Output :

scheduled DFG, frequency, power



Scheduling algorithm

Step 1: Find ASAP schedule of the UDFG.

Step 2: Find ALAP schedule of the UDFG.

Step 3: Determine the mobility graphs for each node.

Step 4: Modify the mobility graph for multicycling.

Step 5: Calculate operating frequency of a FU using delay model.

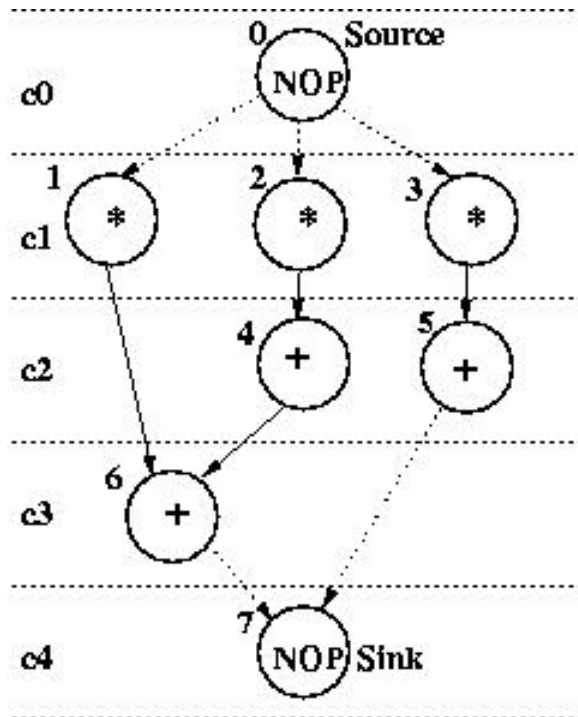
Step 6: Construct the ILP formulations of the DFG.

Step 7: Solve the ILP formulations using LP-Solve.

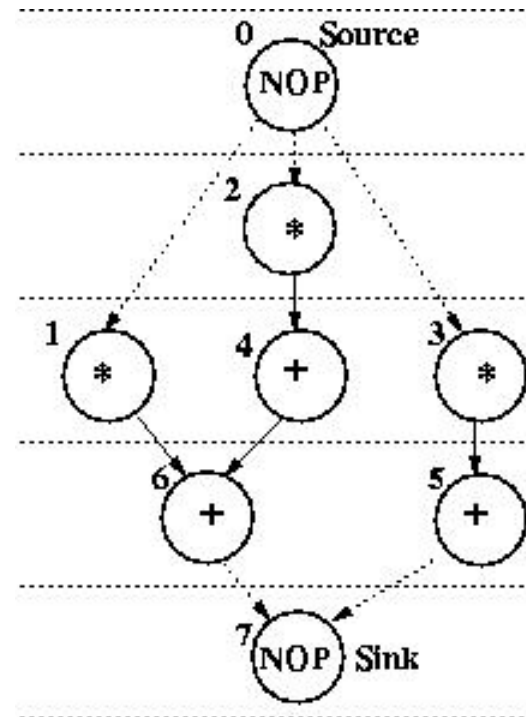
Step 8: Obtain the scheduled DFG.

Step 9: Determine cycle frequency, power.

Example Data Flow Graph

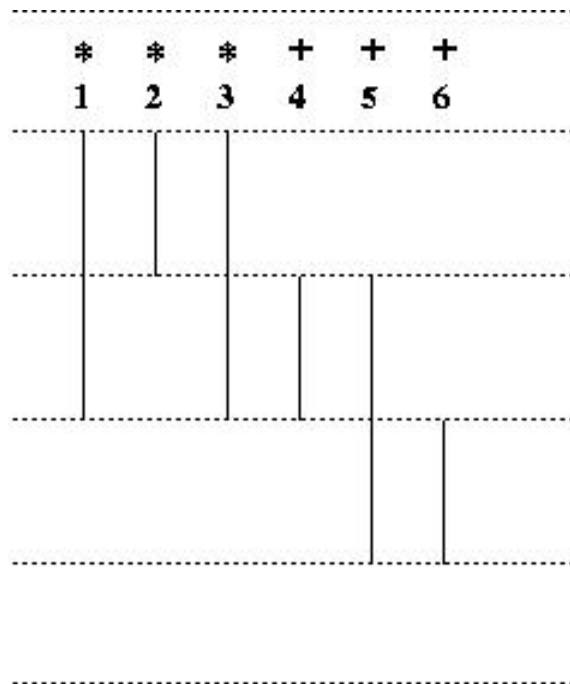


ASAP schedule

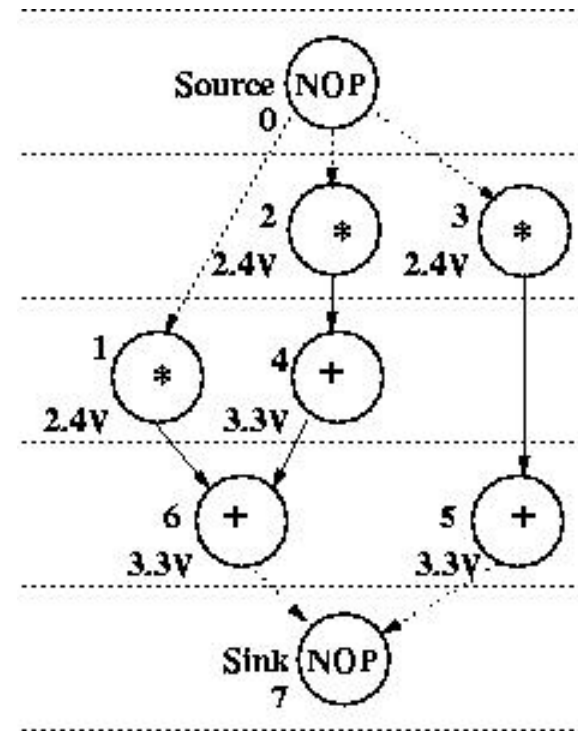


ALAP schedule

Scheduling for MVDFC

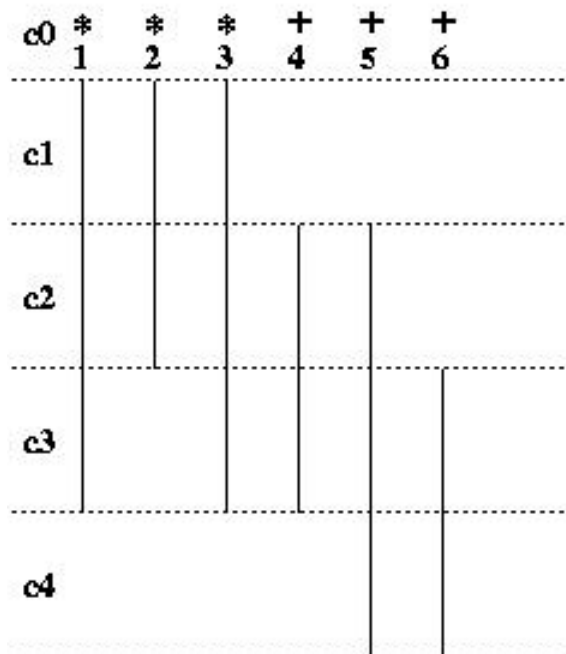


Mobility Graph

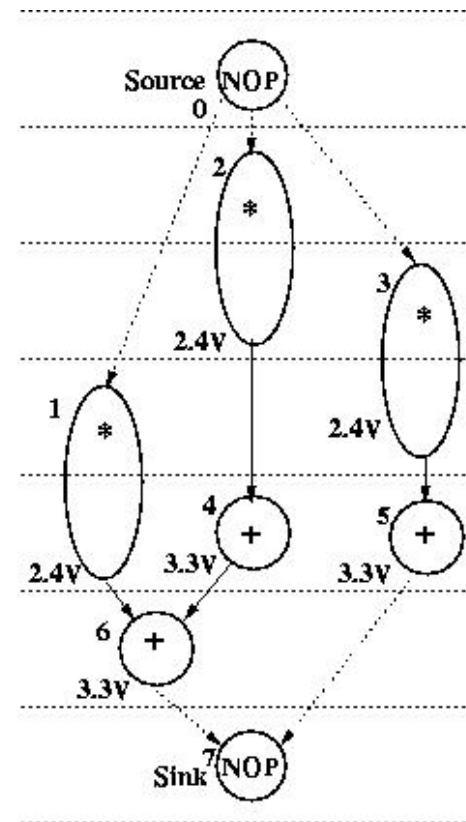


Scheduled DFG (for RC3)

Scheduling for MVMC



Mobility Graph



Scheduled DFG (for RC3)



Experimental results : benchmarks

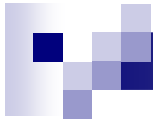
Example circuit (EXP) (8 nodes, 3*, 3+, 9 edges)

FIR filter (11 nodes, 5*, 4+, 19 edges)

IIR filter (11 nodes, 5*, 4+, 19 edges)

HAL solver (13 nodes, 6*, 2+, 2-, 1 <, 16 edges)

Auto-Regressive filter (ARF) (15 nodes, 5*, 8+, 19 edges)



Experimental results : resource constraints

Multipliers		ALUs		Serial No
2.4V	3.3V	2.4V	3.3V	
2	1	1	1	RC1
3	0	1	1	RC2
2	0	0	2	RC3
1	1	0	1	RC4

Experimental results : notations

S : single supply voltage and single frequency operation

D : multiple supply voltages and dynamic frequency clocking operation

M : multiple supply voltages and multicycling operation

P_{pS} , P_{pD} and P_{pM} : peak power in mW

P_{aS} , P_{aD} and P_{aM} : average power in mW

PDP_S , PDP_D and PDP_M : power delay product in nJ

$\Delta P_{pD} = (P_{pS} - P_{pD}) / P_{pS} * 100$: % peak power reduction

$\Delta P_{pM} = (P_{pS} - P_{pM}) / P_{pS} * 100$: % peak power reduction

$\Delta P_{aD} = (P_{aS} - P_{aD}) / P_{aS} * 100$: % average power reduction

$\Delta P_{aM} = (P_{aS} - P_{aM}) / P_{aS} * 100$: % average power reduction

$\Delta PDP_D = (PDP_S - PDP_{DFC}) / PDP_S * 100$: % PDP reduction

$\Delta PDP_M = (PDP_S - PDP_{MC}) / PDP_S * 100$: % PDP reduction

Experimental results : (% reduction)

	RCs	ΔP_{pD}	ΔP_{pM}	ΔP_{aD}	ΔP_{aM}	ΔPDP_D	ΔPDP_M
E X P	1	74	49	73	26	55	0
	2	74	21	73	21	55	0
	3	74	47	71	37	56	0
F I R	1	74	49	74	18	53	0
	2	74	21	73	13	52	0
	3	74	21	72	25	53	0
I I R	1	66	32	68	19	53	0
	2	74	47	73	30	60	0
	3	74	47	72	41	59	5
H A L	1	75	24	73	33	53	0
	2	75	22	73	30	53	0
	3	73	47	72	40	54	0

Reductions using different schedulers

	DFC		Shiue [14]		Martin [9]		Raghuna- than[13]		Mohanty [11]	
Bench- marks	ΔP_{pD}	ΔP_{aD}	ΔP_{pD}	ΔP_{aD}	ΔP_{pD}	ΔP_{aD}	ΔP_{pD}	ΔP_{aD}	ΔP_{pD}	ΔP_{aD}
EXP	73	72	-	-	-	-	-	-	-	-
FIR	71	72	63	NA	40	NO	23	38	71	53
IIR	69	69	-	-	-	-	-	-	-	-
HAL	71	71	28	NA	-	-	-	-	73	70
ARF	73	71	50	NA	-	-	-	-	68	67



Conclusions

- ☐ This paper describes peak and average power reduction schemes at behavioral level through datapath scheduling.
- ☐ The scheduling schemes use ILP based minimization for MVDFC and MVMC mode of circuit design.
- ☐ For both the modes the scheduler could achieve significant peak and average power reduction.
- ☐ The scheduling schemes are useful for data intensive DSP applications.
- ☐ The applicability of the scheduling schemes for pipelining is to be investigated.
- ☐ The effect of switching activity is to be taken into account.
- ☐ The effect on clocking network is to be studied.



Thank you